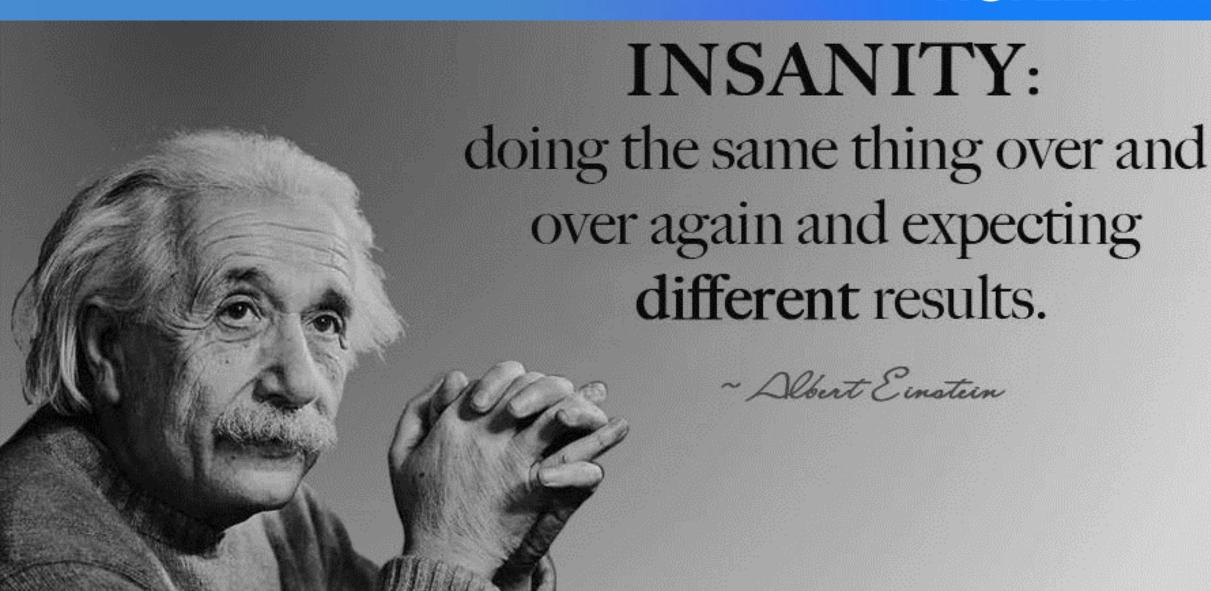
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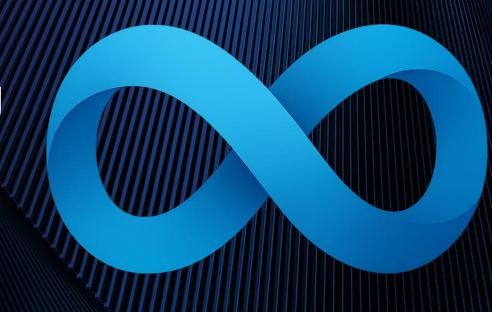




Mobius Virtual Engineering

Faster, Smarter, Data-Driven

Nick Tebbutt / Puneet Mathur



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Trusted by Industry, Independent by Design

HORIBA MIRA is an independent technical advisor & location:

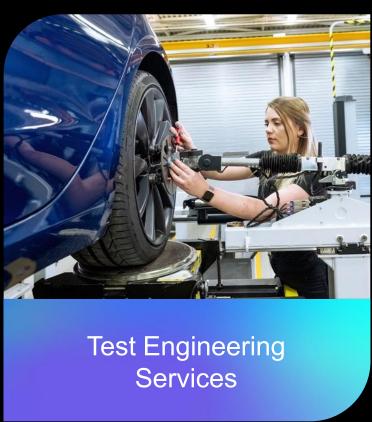
- We combine 80 years of innovation & expertise with modern automotive technology-driven design thinking
- We work globally as a technical partner for OEM's, Regulators, new technology entrants and disruptors
- We built, operated and evolved our own mobility location we understand real user needs
- We provide the independent view of the automotive industry to ensure robust and fit for purpose design
- Leveraging automotive technical consultancy in parallel industries such as defence, water & life science



A global-leader in engineering, research and development

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Traditional development methods can't keep up

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Vehicle systems are more complex than ever — especially EVs and SDVs



Calibrating for optimal energy use, safety, and compliance is slow and costly



Real-world conditions are unpredictable and hard to model in a lab



Regulators will soon demand lifetime compliance, not just Type Approval



Strengthening SDV pipelines with Real-world assurance

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SDVs have redefined the pipeline for software delivery





CI/CD pipelines for continuous software delivery



OTA updates



Modular, service-oriented architectures



SW factories delivering faster prototyping and releases

Critical challenges remain unresolved





Calibrations are treated as one-time event



Validation tied to regulations, ignores real-world use



Costly test fleets required for global test coverage



Rising SW complexity is driving major safety recalls



No standardised framework for lifetime calibration compliance

Mobius builds confidence into SDV pipelines



Calibrations and SW updates validated against global operating conditions



Ensures compliance with regulatory and lifetime requirements



Continuous optimisation across vehicle life



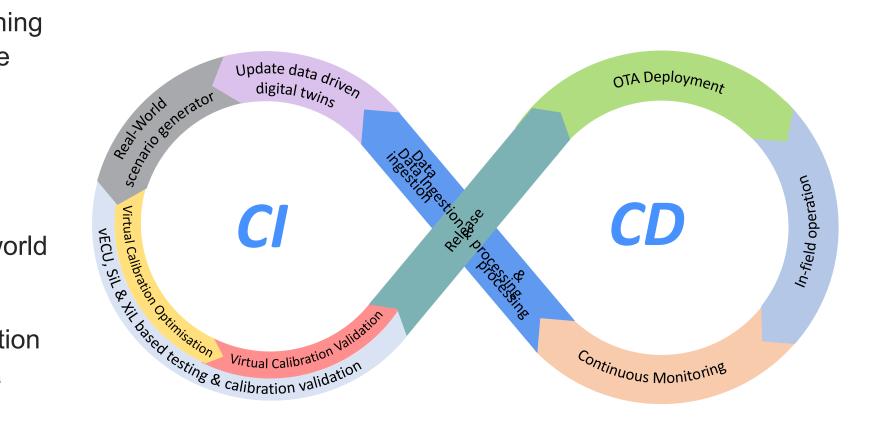
Reduces cost and effort versus traditional fleet testing

SDVs create the pipeline. Mobius solutions ensure what flows through it is safe, compliant, and optimised — for life.

MOBIUS in CI: Real-world compliance assured

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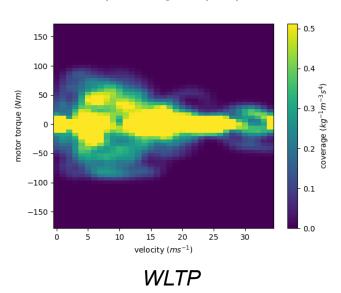
- Digital tools, machine learning and data integration enable virtualised workflows
- Calibration can now be continuous
 - Learning from the real world never stops...
- OTA updates mean calibration is a lifecycle process, not a one-time event

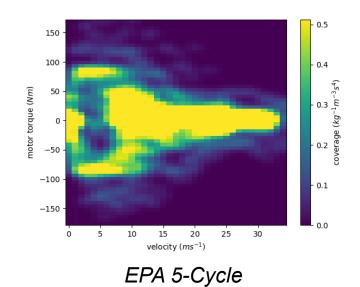


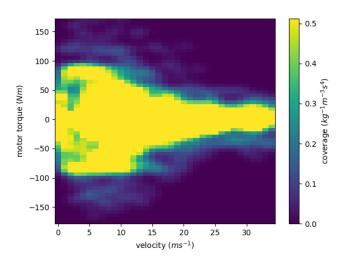
Regulatory testing miss real-world coverage

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e-Motor operating torque points







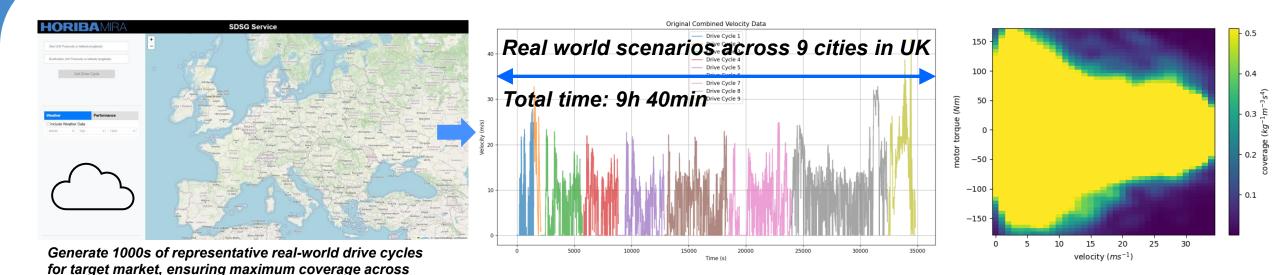
EPA 5-Cycle + WLTP

Challenge

- Calibration optimised and tested to Regulatory drive cycles may not reflect true real-world performance
- Mismatch between lab and real-world performance issues in filed, unhappy customers
- Edge cases missed Calibration not robust in real- world conditions
- Poor global rollout readiness
- Traditional real-world testing is data-heavy, time-consuming, and resource-intensive

Replicate real-world conditions – in minutes

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Our Approach

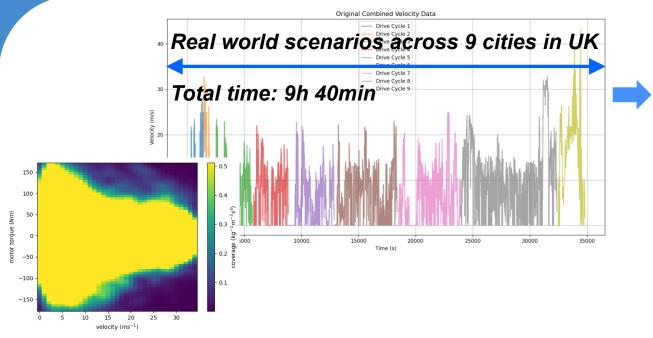
Mobius Scenario: Global real-world scenario generation

- Any country. Any city. Any time.
- Emulate road load, topography, traffic flow, and ambient temperature conditions, virtually in minutes
- No need for global prototype fleets or on-road testing
- Test one calibration across all regions From Nordic cold to Delhi traffic, Peru mountains to Middle-East heat
- Global readiness, with minimal targeted physical regional testing

vehicle performance window

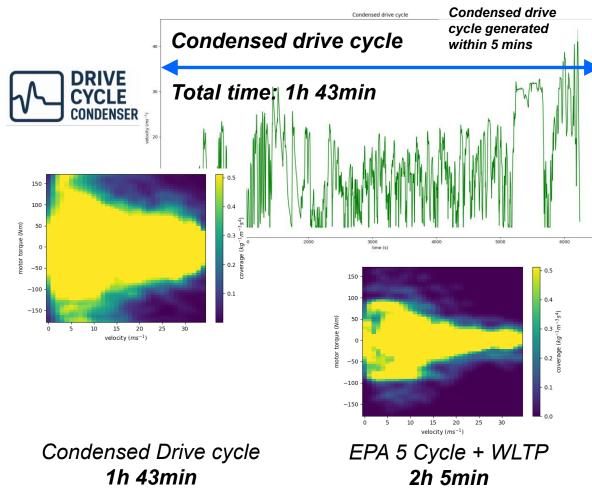
Test *smarter*, not longer

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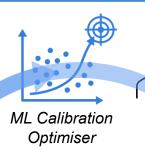
- Extracts only unique real-world driving segments
- Ensure edge case inclusion
- Cuts test time by up to 70%
- Short scenario-rich drive cycles with realistic transitions
- Stronger correlation with real-world performance



Significantly increased coverage compared to regulatory drive cycles, in a shorter time duration

Smarter Calibration starts with Smarter Models

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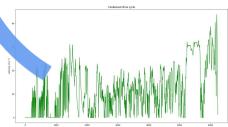
Define your target, let ML do the rest

e.g. Minimise losses, Maximise acceleration, Minimise battery charging time, Minimise CO2, Shifting strategy, etc.



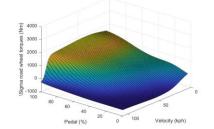
ML Data driven digital twin



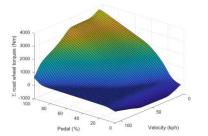


Condensed real-world scenario

ML-powered loop continuously learns and adapts to converge on optimal calibration



ML optimised wheel torque request map – **Minimise losses**



ML optimised wheel torque request map – **Maximise acceleration**

Why Machine learning

- Too many variables, too many interactions
- Learns system behaviour under real-world conditions
- Uncovers interactions no human can calibrate manually
- Converges faster to more accurate, robust calibrations
- One calibration. Globally validated. Minimal targeted region-specific calibration refinement

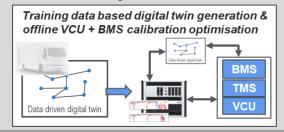
Proven Across Vehicle Systems

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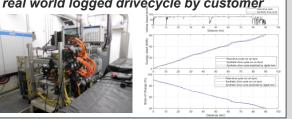
Virtual engineering with Digital Twins: Savings (20-30% in cost &/or time)

- · High accuracy data driven digital twins accelerate calibration and validation, enabling faster iteration cycles and reducing overall testing time and associated costs.
- Scenario generator further reduces the need for in-field data collection for virtual development.

Case study 1: EV Truck battery pack development & integration







Optimising BMS calibration in parallel to pack build saved ~4mo overall Allowed calibration of 90% useable energy to be ready once pack available

Battery charge rate strategies optimised using simulated real-world ambient temperature and driving scenarios

Achieved >97% simulation accuracy vs. measured physical energy use, enabling highconfidence that virtual development & validation approach would deliver under realworld scenarios

Prototype vehicle savings (15-25% in cost)

Reducing the need for multiple physical prototypes due to increased virtual development. Several vehicles can be removed from early prototype fleets

Field Trials Savings (15-25%)

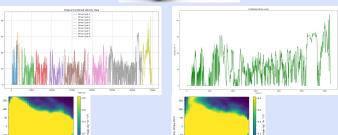
Virtual and XiL based testing allows OEMs to reduce the number of real-world fleet tests and the logistics costs/ CO2 involved in conducting these tests across multiple conditions, globally.

Performance Validation Savings (20-30%)

Performance validation benefits from scenario generators and digital twins, simulating and emulating global conditions in virtual and XiL environment, cutting down on the time and costs associated with real-world performance validation and calibration optimisation.

Case study 2: Whole vehicle efficiency optimisation





High fidelity digital twin generated using data collected from instrumented vehicle via dyno, track and on-road testing

Mobius SG and drive-cycle condenser derived test profile achieved 75% time saving to create equivalent data coverage through physical testing with climatic dyno

Digital twin showed <5% deviation from real-world data before further refinement.

Faster, Smarter, Cheaper – Without compromise

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Replicate scenario-rich global conditions in lab for any powertrain



Reduce test time by up to 70% without cutting coverage



ML uncovers system interactions humans can't tune manually



Fewer prototypes, faster development, globally validated performance



Smarter calibration, lower development cost



Cloud native, secure & OTA-ready

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